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FINAL YAER PROJECT REPORT

GESTURE CONTROL CAR

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Abstract

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Motion Controlled Car is a robot auto which can be controlled by direct human movements. The customer essentially needs to wear a movement device in which a sensor is fused. The sensor will record the improvement of hand over a specific bearing which will achieve the development of the robot in the individual headings. The robot besides, the Gesture instrument are related remotely through radio waves. Customer can interface with the robot in a more very much arranged path as a result of the remote correspondence. We can control the auto using accelerometer sensors related with a hand glove. The sensors are proposed to rebind the remote control that is all things considered used to run the auto. It will allow customer to control the forward, backward, leftward and rightward advancements, while using a similar accelerometer sensor to control the throttle of the auto. To begin the procedure we will require thumb impression start framework after which the auto will be begin.

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