Ultrasonic Home Security System

Degree Project Report



Wasim Ahmed 01-133102-098

Muhammad Adil 01-133102-046

Supervised By Mr. Imran Fareed Nizami

DEPARTMENT OF ELECTRICAL ENGINEERING BAHRIA UNIVERSITY ISLAMABAD



Declaration

We hereby declare that this Project named Ultrasonic Home Security System, based neither as a whole nor as a part here of has been copied out from any source. It is further declared that we have developed this project on our own and the accompanied report entirely on the basis of our personal efforts made under the sincere guidance of our seniors and teachers. If any part of this report is proved to be copied out or found to be reported, we shall standby the consequences. No portion of the work presented in this report has been submitted in support of any other degree or qualification of this or any other University or Institute of learning.

Wasim Ahmed

(01-133102-098)

Muhammad Adil

(01-133102-046)

Acknowledgment

ALLAH the Almighty! We are grateful to YOU, for giving us the strength to take, and for YOUR infinite help to complete this project. Without YOUR help and blessings, we would have never been able to complete this project.

Special thanks to our Parents, who have supported us at every step with a lot of confidence and working with us as a team with much enthusiasm, prayers, affection, love and interest.

Extremely thankful to our supervisor Mr.Imran **Fareed Nizami** for his expert guidance, sincere encouragement and valuable supervision throughout the project.

ABSTRACT

The basic purpose of our project is to with the emergence of new technologies, the field of security has witnessed an exponential rise and it has spread across the entire country. Being engineering students we have decided to take up the challenge and build a portable security systems which is reliable, user friendly, cost effective, scalable and less power consumption and it could help us and others to protect property and privacy and needs no installation and detects invaders on their physical presence. The system uses PIR & Ultrasonic sensor that has a transmitter and a receiver part. The Ultrasonic transmitter periodically emits ultrasonic signals into an open area in front of it, and PIR sensor will look for living things e.g. human on large area. To cover a wide range for Ultrasonic sensor, a rotating servo motor is used to allow the sensor to cover roughly 180 degrees. If the signal ever hits a physical object, it will be reflected back and, the receiver part of the sensor will then capture it with the object considered detected. As the security system sends off a sound alarm (glows LED in our case). Then microcontroller sends the information to PC. That information is then polled by our MATLAB script that information will send as an email to an address set by the owner in advance. The system is also password protected; user can enable or disable system through correct password.

Contents

Ackn	nowledgment	05		
ABS	TRACT	06		
LIST	OF FIGURES	10		
CHA	APTER # 01 Introduction			
1.1	Ultrasonic Home Security System	12		
1.2	Objective	12		
1.3	Motivation	13		
1.4	Aims	13		
1.5	Challenges	13		
1.6	targets	14		
	1.6.1 Essentials	14		
	1.6.2 Preferred	14		
СНА	APTER # 02 Literature Review			
2.1	Introduction	16		
2.2	Comparison between home security systems	16		
2.3	Ultrasonic and PIR sensor	17		
2.4	Different Types of sensor	17		
	2.4.1 Active sensor	17		
	2.4.2 Passive sensor	17		
2.5	Choosing security system	18		
	2.5.1 Advantages	18		
2.6	Techniques for security system	19		
2.7	Importance of Our Project	19		
СНА	APTER 3 Components and Modules			
3.1	OVERVIEW	21		
3.2	List of components			
3.3	AT89C51Micro-controller			
	3.3.1 Features of AT89c51	22		
3.4	Hc-sr04 Ultrasonic sensor	23		
	3.4.1 Features of ultrasonic sensor	23		

3.5	Futaba	S3003 servo motor			
3.6	2N222	2 Transistor			
3.7	Max23	32 serial communication IC			
3.8	Servo	Motor Drive Module			
3.9	Serial	to USB cable for communication			
3.10	PIR Se	ensor			
	3.10.1	Features of PIR Sensor			
СНАН	PTER#	04 Analyses			
4.1	Contro	ol System			
4.2	Positio	oning			
	4.2.1	Security Level Design			
4.3	Energy	Supply			
4.4	Comm	unication			
4.5	MATL	.AB			
4.6	Safety	Issues			
4.7	Netwo	rk Flow Diagram			
4.8	Serial	Port			
4.9	Setting the Serial Port Baud Rate				
4.10	Analys	sis of Security System			
4.11	PIR wo	orking			
СНАН	PTER#	05 Implementation			
5.1	Hardw	rare Implementation			
	5.1.1	Servo Motor			
	5.1.2	Microcontroller Interfacing			
	5.1.3	Servo Motor Drive Circuit			
		5.1.3.1 Calculations			
		5.1.3.2 Energy supply			
	5.1.4	Ultrasonic Sensor Communication And Testing			
	5.1.5	PIR Sensor Communication And Testing			
	5.1.6	Complete Hardware			
5.2	Softwa	are Prototype Designing			
	5.2.1	Hardware Implementation			

	5.2.2 Ultrasonic Sensor			
	5.2.3 PIR Sensor			
5.3	Servo Motor Drive Circuit			
	5.3.1 Serially Transmission data			
СНАР	TER # 06 Tests and Results			
6.1	Circuit Testing			
6.2	Software Prototype Testing			
6.3	Hardware Testing			
	6.3.1 Test Cases			
6.4	Ultrasonic Sensor Communication Testing			
6.5	PIR communication and Testing			
6.6	MATLAB Result			
6.7	Distance Measurement Accuracy			
6.8	Speed of detection			
6.9	Detection Accuracy			
6.10	E-mail Notification			
6.11	Results			
6.12	Problems Faced			
	6.12.1 Problems Countered			
СНАР	TER # 07 OUTCOMES			
7.1	Challenges Set forth			
7.2	Achievements			
7.3	Future Enhancement			
7.4	Conclusion			
7.5	Future Work			
7.6	IEEE Rules and Regulations			
Refere	ences			

LIST OF FIGURES

Figure 3.1 Overview diagram	21
Figure 3.2 Pin configuration of 89c51 microcontroller	22
Figure 3.3 Hc-sr04 ultrasonic sensors	23
Figure 3.4 Working of servo motor	24
Figure 3.5 Diode and its symbol	25
Figure 3.6 Max232 ic symbol	25
Figure 3.7 Block diagram of servo motor drive circuit	26
Figure 3.8 PIR sensor symbol	27
Figure 4.1 Microcontroller interface with other modules	
Figure 4.2 Power supply's interface with other modules	
Figure 4.3 Overall net flow diagram	
Figure 5.1 Project breakdown	
Figure 5.2 Servo motor angle position	
Figure 5.3 Microcontroller interface with ultrasonic and PIR sensor	
Figure 5.4 Drive circuit for servo motors	
Figure 5.5 Complete circuit diagram	
Figure 5.6 servo motor drive circuit	
Figure 5.7 MATLAB interfacing	41
Figure 6.1 Complete diagram on proteus	
Figure 6.2 Sensor working	
Figure 6.3 Password protected	
Figure 6.4 Simulation for servo motor movement as 0 to 90 degree	
Figure 6.5 MATLAB Results in case of correct password and detection of object	
Figure 6.6 MATLAB Results in case of wrong password	