



FINAL YEAR PROJECT REPORT

**HAND GESTURE CONTROLLED DRONE USING
MACHINE LEARNING**

In fulfillment of the requirement

For degree of

BS (COMPUTER SCIENCES)

By

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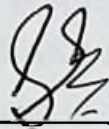
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DECLARATION

We hereby declare that this project report is based on our original work except for citations and quotations which have been duly acknowledged. We also declare that it has not been previously and concurrently submitted for any other degree or award at Bahria University or other institutions.

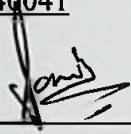
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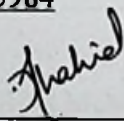
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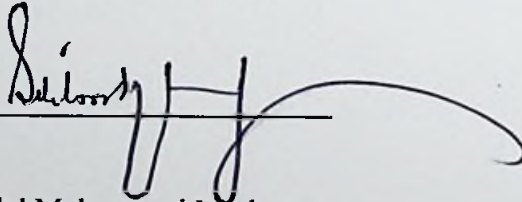
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APPROVAL FOR SUBMISSION

We certify that this project report entitled “**HAND GESTURE CONTROLLED DRONE USING MACHINE LEARNING**” was prepared by **SHEEZA SHAH, LAIBA SHAHID AND KINZA FATIMA**, and has met the required standard for submission in partial fulfilment of the requirements for the award of Bachelor of Computer Science (Honours) at Bahria University.

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HAND GESTURE CONTROLLED DRONE USING MACHINE LEARNING

ABSTRACT

The objective of this project is to develop a hand-gesture controlled drone using machine learning. This project uses the Convolution Neural Network model, combined with the background elimination to detect different hand gestures, it takes a running average of the background for 30 frames and afterward utilize that running normal to identify the hand that must be presented after the foundation has been appropriately perceived. A background elimination algorithm removes the hand picture from webcam and utilizes it to prepare to anticipate the kind of signal that is. After trials and errors, a suitable set of training parameters are defined and network structure that contains **seven** hidden convolution layers with “**relu**” as the activation function and **one** fully connected layer. The network is trained across **fifty** iterations with a batch size of **sixty-four**. The model achieves an accuracy of **94.4%** on the testing results. The proportion of preparing set to approval set is 1000:100. The framework first continues with the pre-procedure of the caught picture by wiping out all the undesirable parts in a constant video succession utilizing OpenCV and Python. Separating, division, resizing and includes extraction are additionally acted all the while. Next, a feed forward procedure through the system is summoned to yield a yield lattice. In light of the yield network, the perceived motion can be resolved. This system is designed to customize the network for an individual user.

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