# Couette-Poiseuille flow of kerosene based ferrofluid in a rotating channel with mass transfer and slip effect



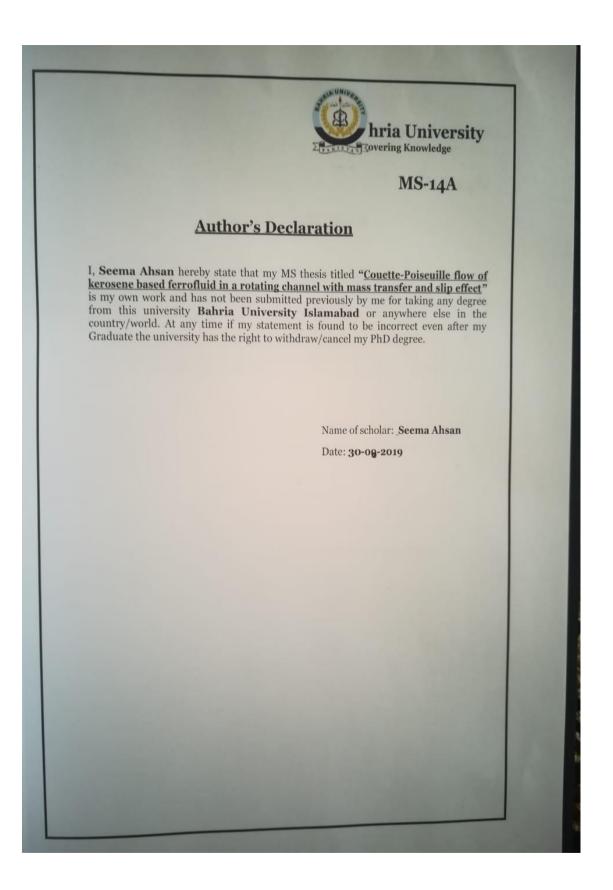
## By Seema Ahsan

## *MS THESIS SESSION 2017-2019*

Department of Computer Sciences Bahria University, Islamabad Campus 2017-2019

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Date: 30-09-2019 Name: Dr. Jafar Hasnain	
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## **Dedicated to**

I am dedicating this thesis to my beloved sister **Neelam Aslam** who has meant a lot to me. Although she is no longer in this world. Her memories continue to regulate my life. Though your life was short, I will make sure your memory lives as long as my life shall live. May Almighty Allah grant you Jinnah Firdaws Ameen.

## Acknowledgment

In the name of Allah the most Merciful and Beneficent

First and foremost praise is to ALLAH, the Almighty, the greatest of all, on whom ultimately we depend for sustenance and guidance. Countless salutations be upon the Holy Prophet MUHAMMAD (PBUH) who ordained every Muslim to yearn for knowledge from cradle to grave. I would like to thank Almighty Allah for giving me opportunity, determination and strength to do my research. His continuous grace and mercy was with me throughout my life and ever more during the tenure of my research.

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> SEEMA AHSAN Bahria University September 2019

### Abstract

The aim of this thesis is to look into the problem of Couette-Poiseuille flow of kerosene based ferrofluid passing through rotating permeable channel. Heat and mass transfer analyses are carried out to see the behavior of ferrofluid in such situation. In this problem ferrofluid is subjected to the effects of magnetic field and velocity slip boundary condition. By means of transformations, the consequential governing equations are developed into coupled non-linear ordinary differential equations. By using shooting method, numerical results of these non-linear ordinary differential equations is attained. The physical impact of all fluid parameters on flow arenas are presented graphically and described in detail. The primary velocity of the fluid is discovered to increase by increasing the values of Reynolds numbers, magnetic parameters and slip parameters on the lower wall. However secondary velocity decreases with magnetic parameter. Also fluid temperature increases by rotation parameter, Eckert number and upper wall motion parameter. Mass transfer in the fluid increases by the greater value of Schmidt number along with chemical reaction parameter.

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#### Nomenclature

V	suction/injection velocity
U	dimensionless velocity
${U}_0$	upper wall velocity
и, w	velocity components
U,W	dimensionless velocity components
<i>x</i> , <i>y</i> , <i>z</i>	cartesian coordinate
L	channel length
$T_1$	upper wall temperature
$T_{f}$	hot fluid temperature
Т	nanofluid temperature
Sh	Sherwood number
Re	suction/ injection Reynolds number
$R_0$	fluid rotation parameter
$q_{_W}$	wall heat flux
$q_{\scriptscriptstyle m}$	wall mass flux
t	transpose of matrix
Pr	Prandtl number
J	electric current density
Nb	Brownian motion parameter
Р	nanofluid pressure
Nt	thermophoresis parameter
Nu	Nusselt number
Le	Lewis number
k	thermal conductivity
$h_{_f}$	heat transfer coefficient
Ec	Eckert number
$D_{T}$	thermophoresis diffusion coefficient
1	

$D_{\scriptscriptstyle B}$	Brownian diffusion coefficient
$m{C}_{pf}$	specific heat and constant temperature
$C_{f}$	skin friction
С	nanoparticles connection
$C_1$	upper wall concentration
$C_0$	lower wall concentration
Bi	Biot number
$B_0$	strength of applied magnetic field
$L^{*}$	velocity gradient
$k_n$	reaction rate of the nth-order
	homogeneous chemical reaction.
$A_{l}^{*}$	first Rivlin-Erickson tensor
m	hall current parameter
Sc	Schmidt number
$n_p$	shape factor
$\omega_{e}$	cyclotron frequency
$ au_{e}$	electron collision time
τ	ratio between heat capacity of
	nanoparticles and fluid
Ω	angular velocity
$\alpha_{_f}$	thermal diffusivity coefficient

**Greek letters** 

λ

 $\delta$ 

β

η

 $\theta$ 

upper wall motion
variable viscosity coefficient
viscosity variation parameter
dimensionless variable
dimensionless temperature

$\phi$	dimensionless concentration
μ	dynamic viscosity
U	kinematic viscosity coefficient
$\sigma$	electrical conductivity
$lpha_{_{nf}}$	thermal diffusivity
$ ho_{nf}$	effective density
$\mu_{nf}$	effective dynamic viscosity
$\left( ho C_{p} ight)_{nf}$	heat capacitance
$\kappa_{nf}$	thermal conductivity
arphi	volume fraction
$\mu_{_f}$	dynamic viscosity
$ ho_{_f}$	density for ferrofluid
$ ho_{s}$	density for base fluid
$\left( oldsymbol{C}_{p} ight) _{f}$	specific heat parameter
$\mathcal{K}_{f}$	thermal conductivity
$\left( \boldsymbol{C}_{p} \right)_{s}$	specific heat parameter
Ks	thermal conductivity for base fluid
α	slip parameter
$\varphi$	nanoparticle volume fraction
γ	Chemical Reaction parameter

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## Chapter 1

## Introduction

#### 1.1 Overview

The foremost purpose of this chapter is to emphasize on associated fundamental definitions and laws that describe the flow phenomena in a channel made by two infinite parallel walls viz. continuity, heat, mass transfer and momentum. The fundamental concepts of techniques for solving the governing equations are also presented.

#### 1.2 Fluid

Fluid is a matter that can flow and which cannot have any specific shape. Some aspects of fluid flow are fluid evenness, fluid squeezability and fluid spinning. Fluid flow rely on the viscosity of fluid. Amount of a fluid's confrontation to flow is called viscosity. There are two kinds of fluid i.e. Newtonian and non-Newtonian fluid. Newtonian fluids are described by relation in shear rate & shear stress with a simple linear relation. But when a fluid does not satisfy the viscosity's law then it is known as non-Newtonian. Viscosity of non-NF is dependent on shear rate. Because the earth is 75% water-covered and 100% aircovered, there is a huge range of fluid mechanics and almost every human effort touches. Meteorology, physical oceanography and hydrology sciences are connected with natural fluid flows. They are extensively employed in food & nutrients industry, petroleum industry, chemical engineering, biological interpretation as well as some other fields.

#### 1.3 Nanofluid

Nanofluid (NF) is a liquid that contains particles of nanometer size called nanoparticles (NPs). These kinds of fluids are produced in a base fluid with colloidal

suspensions of NPs. The NPs utilized in nanofluids (NFs) are ordinarily made of oxides and metals. Normal base liquids are oil and water. NFs have different properties that are helpful in various solicitations in heat exchange, energy units, microelectronics, medical procedures, crossover fueled motors, local fridge, heat exchanger, chiller, atomic reactor coolant, in granulating, machining and in space innovation. There are different models that can best describe the characteristics of NFs. One of them is a Buongiorno fluid model. Buongiorno model examines the reaction of Brownian motion and thermophoresis on flow, mass and heat transfer.

#### 1.4 Ferrofluid

Another type of NF is ferrofluid (FF) which turns out to be highly charged within the sight of a magnetic field. FFs contain nanoscale ferromagnetic or ferrimagnetic particles in a transporter liquid. These two liquids have altogether different applications subsequently. The characteristics of FF make it beneficial for various applications. In computer hard drives and other rotating shaft engines, FF is used in rotating seals. To dampen vibrations, laoudspeakers use FF. As a contrast agent for magnetic resonance imaging (MRI), FF is used in medicine.

#### **1.5 Hall effect**

The Hall effect (HE) is the creation of an electrical conductor voltage difference, transverse to an electrical current in the conductor and perpendicular to the current to an applied magnetic field. HE is also used in bicycle wheels and some electronic types of systems e.g. electronic campuses. Now a days mostly HE are used in smart phones, as well as in some guns and GPS systems. Moreover, HE analogue multiplication application is used in small computers.

#### 1.6 Mass transfer

Mass transfer is an imperative procedure as a result of its appearance in a few logical controls that require convective exchange of molecules and atoms. Mass exchange has two fundamental types i.e. purely diffusive mass transfer and convective mass transfer. It is experienced in chemical procedure in both building and partition forms. Periodically, a chemical procedure might be utilized to quicken the mass transport rate. In this regard, Lorentz force is the very important part used to control the stream in such circumstances. On the other hand, in several chemical engineering procedures, mixed mass and heat transfer, chemical reaction problems are excellent significance, thus attracting significant attention in latest years. In addition, chemical reactions have usually been categorized as homogeneous and heterogeneous. The chemical engineering which is shown in the principle part of the fluid, it has various compound structure and present-day applications such as in the gathering of stoneware generation, polymer creation, sustenance getting ready, etc.

#### 1.7 Magnetohydrodynamics

Magnetohydrodynamics (MHD) is the study of the magnetic characteristics and behavior of the liquids. Rotating flow of MHD viscous fluids has huge applications in astrophysics, industrial design and geophysics. MHD play a key role in evaluating the mass ejections, corona structure and triggering solar flares.

#### **1.8 Slip flow**

In the no slip flow regime, the relative speed of the liquid and the wall is zero. But the relative speed is non-zero at the surface in the case of slip flow. There are numerous conditions when the liquid is particulate like polymer solutions and emulsion suspension and at that point slip condition is more suitable.

#### 1.9 Basic Laws

The basic equations with heat exchange explaining the fluid flow are as under:

#### **1.1.1 Equation of continuity**

The continuity equation for incompressible fluid is  $\nabla V = 0.$  (1.1)

### 1.1.2 Conservation of momentum equation

$$\rho \mathbf{b} \cdot (\mathbf{V} \cdot \nabla) \mathbf{V} + \operatorname{div} \mathbf{\tau} + 2\mathbf{\Omega} \times \mathbf{V} = v \nabla^2 \mathbf{V} + \frac{1}{\rho} \mathbf{J} \times \mathbf{B} - \frac{1}{\rho} \nabla p = \rho \frac{d \mathbf{V}}{dt}, \qquad (1.2)$$

together with the generalized law of Ohm, which takes into consideration the present Hall

$$\boldsymbol{j} + (\boldsymbol{j} \times \boldsymbol{B}) \frac{\omega_e \tau_e}{\beta_o} = \sigma (\boldsymbol{q} \times \boldsymbol{B} + \boldsymbol{E}).$$
(1.3)

#### 1.1.5 Conservation of energy equation

$$\rho \boldsymbol{c}_{\boldsymbol{p}} \left( \frac{\mathrm{dT}}{\mathrm{dt}} \right) = -di \boldsymbol{v} \boldsymbol{q} + \boldsymbol{\tau}^* \cdot \boldsymbol{L}^*, \tag{1.4}$$

Here

$$\boldsymbol{\tau}^* = \boldsymbol{\mu} \boldsymbol{A}_1^* - \boldsymbol{p} \boldsymbol{I}^*, \tag{1.5}$$

$$\boldsymbol{A}_{1}^{*} = \nabla \boldsymbol{V} + \left(\nabla \boldsymbol{V}\right)^{t} \boldsymbol{.}$$

$$(1.8)$$

#### **1.1.6 Concentration equation**

$$\frac{dC}{dt} = D\nabla^2 C + k_n C^n.$$
(1.9)

#### 1.10 Solution methods

Differential equations (ordinary and partial differential) are commonly used in architecture and technological innovative world problems. Because of long lasting nonlinearity, this is simply not possible to solve these types of equations. By the use similarity transformations, ordinary differential equations (ODEs) are derived from partial differential equations (PDEs) that can be further solved numerically. The basic way of the method used to solve the present problem is appended below.

#### 1.10.1 Runge-Kutta Method

Several numerical methods are available to solve the ODEs by the use IVP (initial value problems). C. Runge and W. Kutta (German Mathematicians) presented precise as well as successful computational techniques named as Runge-Kutta (R-K) techniques. Out of all, fourth order R-K technique is more productive. Mostly, IVP of second order is articulated as

$$y'' = h(x^*, y^*, (y^*)'), \qquad (1.10)$$

with initial condition

$$y^{*}(x_{a}^{*}) = y_{a}^{*}, \quad ((y^{*}))(x_{a}^{*}) = c$$
 (1.11)

By defining equation (1.10) as

$$y' = z = l(x^*, y^*, z^*),$$
 (1.12)

and

$$z' = h\left(x_{o}^{*}, y_{o}^{*}, z_{o}^{*}\right), \tag{1.13}$$

and the initial conditions (ICs) are

$$y^{*}(x_{a}^{*}) = y_{a}^{*}, \quad z^{*}(x_{a}^{*}) = c$$
  
(1.14)

For Eqs (1.3) and (1.4), the R-K method is defined as under:

$$y_{j+1}^{*} = y_{j}^{*} + \frac{1}{6} (t_{1} + t_{2} + t_{3} + t_{4}), \qquad (1.15)$$

and

$$z_{j+1} = z_j + \frac{1}{6} \left( s_1 + s_2 + s_3 + s_4 \right), \tag{1.16}$$

where

$$t_{1} = gl(x_{j}^{*}, y_{j}^{*}, z_{j}^{*}), \qquad s_{1} = gh(x_{j}^{*}, y_{j}^{*}, z_{j}^{*}),$$

$$t_{2} = gl\left(x_{j}^{*} + \frac{h}{2}, y_{j}^{*} + \frac{t_{1}}{2}, z_{j}^{*} + \frac{s_{1}}{2}\right), \quad s_{2} = gh\left(x_{j}^{*} + \frac{h}{2}, y_{j}^{*} + \frac{t_{1}}{2}, z_{j}^{*} + \frac{s_{1}}{2}\right),$$

$$t_{3} = gl\left(x_{j}^{*} + \frac{h}{2}, y_{j}^{*} + \frac{t_{2}}{2}, z_{j}^{*} + \frac{s_{2}}{2}\right), \quad s_{3} = gh\left(x_{j}^{*} + \frac{h}{2}, y_{j}^{*} + \frac{t_{2}}{2}, z_{j}^{*} + \frac{s_{2}}{2}\right),$$

$$t_{4} = gl\left(x_{j}^{*} + h, y_{j}^{*} + t_{3}, z_{j}^{*} + s_{3}\right), \quad s_{4} = gh\left(x_{j}^{*} + h, y_{j}^{*} + t_{3}, z_{j}^{*} + s_{3}\right),$$

where g is the step size identified as

$$g = \frac{x_{n_0}^* - x_0^*}{n_0}.$$
 (1.17)

In Eq. (1.17), step size is  $n_0^+$ ,  $x_n^{*+}$  is the last value and  $x_0^{*+}$  is initial value.

#### 1.10.2 Shooting method

One of the numerical techniques used to fix that problem of the two-point limit value is known as the method of shooting. In this technique, by assuming the unknown conditions, the boundary value problem (BVP) of greater order is first changed to an IVP. In fluid mechanics and mathematical physics, shooting technique practice as an important method. The subject of the third order boundary value is regarded:

$$u''' = \Phi(u', u'', y^*, u^*), \tag{1.18}$$

with BCs

$$u'(0)^* = 0, \, u'(g) = A^*, \, u(0)^* = \alpha^*.$$
(1.19)

Here y = 0 to y = g, is solution domain for  $\Phi$  and unknown IC is considered as

$$u''(0) = r_1. (1.20)$$

Eq. (1.18) is reducing as

$$u' = v, \tag{1.21}$$

$$v' = w, \tag{1.22}$$

$$w' = f\left(y, u, v, w\right),\tag{1.23}$$

whereas the ICs for above equations are follows

$$v(0) = 0, u(0) = \alpha_1 \text{ and } w(0) = r_1.$$
 (1.24)

By differentiating Eqs. (1.23) - (1.24) w.r.t.  $r_1$  like

$$v' = f' \times W + f' \times V + f' \times U, \tag{1.25}$$

where

$$U = \frac{\partial}{\partial r_1}(u), \mathbf{W} = \frac{\partial}{\partial r_1}(w), \mathbf{V} = \frac{\partial}{\partial r_1}(v), \tag{1.26}$$

and

$$V(0) = 0, U(0) = 0, W(0) = 1.$$
 (1.27)

As Eq. (1.23) and Eq. (1.25) represent the two systems of IVP with initial conditions (1.24) and (1.27). The assumed value of  $r_1$  must meet the requirement  $u'(h) = \beta$  or  $u(y, r_1)$ ,  $v(y, r_1)$  and  $w(y, r_1)$  may expressed the results of initial value problems (IVP), one looks for the value of  $r_1$  such that

$$\theta_1(r_1) = -\beta + u(g, r_1) = 0, \quad (say)$$
 (1.28)

With the help of Newton's method,  $r_1$  can be upgraded as

$$r_{1}^{(j+1)} = r_{1}^{(j)} - \frac{\theta_{1}\left(r_{1}^{(j)}\right)}{\theta_{1}'\left(r_{1}^{(j)}\right)}.$$
(1.29)

Putting  $u(h, \mathbf{r}_1) - \beta = 0 = \theta_1(r_1)$ , (say) in Eq. (1.19), we get

$$-\frac{\left(u\left(h,\mathbf{r}_{1}^{(j)}\right)-\beta\right)}{\frac{\partial u}{\partial r_{1}}\left(h,\mathbf{r}_{1}^{(j)}\right)}+r_{1}^{(j)}=r_{1}^{(j+1)}.$$
(1.30)

Eqs. (1.21) - (1.23) with Eq. (1.27) are explained as under:

(i) The  $r_1$  is selected as missing IC in Eq. (1.21) and symbolizing it by  $r_1^{(1)}$ 

- (ii) Eqs. (1.21) (1.23) by the ICs (1.27) is integrated 0 to g.
- (iii) with ICs (1.25) the Eq. (1.23) is solved as an IVP from 0 to g.
- (iv) Substituting  $u(g, \mathbf{r}_1^{(1)}) \& U(g, \mathbf{r}_1^{(1)})$  in Eq. (1.28) we get

$$r_{1}^{(2)} = r_{1}^{(1)} - \frac{\left[u\left(g, r_{1}^{(1)}\right) - \beta\right]}{U\left(g, r_{1}^{(1)}\right)}.$$

(v) All above options are recurrent while the solution meets the condition of the specified limit.

## Chapter 2

#### **Literature Review**

#### 2.1 Overview

In this chapter we represented the literature study related to nanofluid, Hall effect, mass transfer, MHD and slip flow.

#### 2.2 Related work

The NPs utilized in nanofluids (NFs) are ordinarily made of oxides and metals. Choi [1] investigated NFs and also indicated that they have novel physical substantial attributes and the particles within it possess higher thermal conductivities. Seo et al. [2] studied that thermal flow qualities of a FF in the existence of magnetic field. Goharkan [3] explained the constrained convective heat exchange of water-based FF exposed to variable magnetic field. Impact of magnetic field on basic heat motion of FF flow bubbling in an upright annulus explored by Aminfar et al. [4]. Murshed and Estelle [5] presented an inclusive review on analysis and progression along with features of NFs for their innovative heat transport applications. If tikhar et al. [6] firstly focused on measuring mass diversity in NFs though in the second phase they concentrated on convective mass exchange in NFs. Qiang and Xuan [7] investigated the flow possessions of Cu-water NF, friction factor of cu-water NF and convective 1heat transfer for turbulent & laminar flow under the single phase flow and discovered the new convective heat transfer association established in tubes for NF. Ganji and Sheikholeslami [8] investigated FF flow and thermal transfer phenomena through the semi-annulus magnetic field enclosure. Ganji and Sheikholeslami [9] again addressed the nature of NF flows through differential conversion methods between Brownian movement and heat transfer between parallel plates. Together with thermal

radiation in a channel, Kandelousi & Mahmoodi [10] explored the heat transfer and Kerosene–alumina nanofluid flow with the presence of magnetic field. Fakour et al. [11] examined both NF flow and heat exchange across a channel.

The Hall effect is the production of Hall voltage normal to both the magnetic field and current by means of a magnetic field carrier. With the presence of HE, Attia et al. [12] investigated the impact of uniform magnetic field for transient Couette flow of a non-Newtonian Bingham fluid. Priyadarsan et al. [13] researched that, owing to Hall parameters, the velocity reduces and the skin friction coefficient increases. When a magnetic field is applied, the induction of strong magnetic field results in complicated phenomena along with Hall currents (HC), Joule's heating etc, as Cramer and Pai [14] have stated in an electrical flow regime. The Hall effects on free and forced convective rotating flow was examined by Rao and Krishna [15]. Attia [16] studied the effect of HC on Couette-Poiseuille (CP) flow of viscoelastic fluid owing to heat transfer. Chauhan and Agrawal [17] researched that the Hall current effects on MHD flow in a partly filled rotating channel with a porous medium. The HC and rotation impacts reported by Sarkar et al. [18] on steady hydromagnetic CP flow. Jha and Apere [19] are explored combined effects of HC in a rotating channel with ion-slip present on MHD CP flow. Makinde et al. [20] investigated numerically the MHD CP flow of variable viscosity NF with mass and heat transfer through parallel walls.

Mass transfer is an imperative procedure as a result of its appearance in a few logical controls that require convective exchange of molecules and atoms. Fang et al. [21] presented the experimental study on mass transfer in NF. Seth and Nandkeolyar [22] claimed that angle of inclination accelerates primary and secondary flow at the same time magnetic field retards it. Serna [23] with the help of heat and mass transfer studied the heat properties in steady two-dimensional NFs boundary layer. Singh and Chamkha [24] studied for second order slip flow over a continually permeable shrinking wall. Ojjela and Kumar [25] investigated the mass and heat exchange of micropolar fluid flow across a channel in the presence of Ion slip and Hall current. Fakour et al. [26] presented the solution of chemical reaction for micropolar fluid flow through the channel analytically as well as numerically. Tetbirt et al. [27] studied the micropolar fluid flow with magnetic field and convective heat exchange of viscous flued in vertical channel by using numerical analysis.

Ali et al. [28] examined the problem of the presence of a magnetic field over a folding sheet for an incompressible viscous fluid of the continuous stagnation point MHD. Makinde and Onyejekwe [29] investigated MHD generalized Couette flow and heat transfer numerically. Several writers [30–34] described regular / NF thermal exchange hydromagnetic flow in different geometries. Fersadou et al. [35] claimed that the flow of NF flow with magnetic field in a vertical channel. Many researchers about MHD in near past has been presented in [36-38].

There's a lot of conditions when the liquid is particulate, such as suspension emulsion, polymer solutions and froth, at that point slip condition is more suitable. In this regard, various authors were presented their research work such as Wang [39] studied the slip effects over an extending sheet for the flow of viscus fluid. Aziz [40] studied the impact of slip over flat plate in the flow of the boundary layer. The variation of velocity and thermal slip condition on the flow of eclectically conducting fluid past a sheet investigated by Hayat et al. [41]. Abbas et al. [42] were presented the analytic study on two phase flow of FF and viscous fluid in an inclined channel with slip velocity. The variety of slip impacts on NF flow past a sheet was discussed by Nandy and Mahpatra [43]. For some relevant studies readers are referred to see [44-50].

## **Chapter 3**

# Hall effects on Couette-Poiseuille flow of MHD nanofluid in a rotating channel with variable viscosity

#### **3.1 Introduction**

This chapter describes the hydromagnetic CP flow of NF with mass transfer through parallel plates. Brownian motion, thermophoresis, Joule heating, Hall effects and viscous dissipation are included in the nonlinear model describing this problem. The acquired equations are solved numerically by the aid of fourth order R–K integration system. The consequences of numerous parameters are also examined via graphs. This chapter is a review of the paper by Makinde et al. [20].

#### 3.2 Problem development

Assumed two parallel walls, through which we have an incompressible electrically and thermally conducting NF with magnetic field  $B_0$  applied transversely to the flow. Both the NF and channel rotate about y -axis with  $\Omega$ . In this channel, flow is generated due to the combined action of applied pressure gradient along x -axis, the uniform motion of the upper wall  $U_0$ . The upper wall temperature is  $T_1$  and lower wall is  $T_f$  with heat coefficient  $h_f$ . In this chapter, heat transfer investigation is also utilized with the help of Brownian motion. Figure. 3.1 represent fluid flow model. Since channel walls are infinite in x and z -directions, all parameters depend on y except pressure.

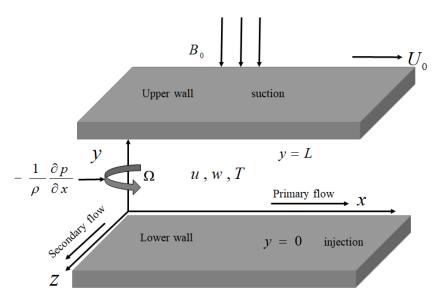


Figure.3.1: Fluid flow model

In view of above, following the Buongiorno [51] the main equations are given as

$$-V\frac{du}{dy} + 2w\Omega = \frac{1}{\rho_f}\frac{d}{dy}\left(\mu_f\frac{du}{dy}\right) - \frac{\sigma B_0^2\left(u - U_0 + mw\right)}{\rho_f\left(1 + m^2\right)},$$
(3.1)

$$-V\frac{dw}{dy} - 2\Omega(u - U_0) = \frac{1}{\rho_f} \frac{d}{dy} \left(\mu_f \frac{dw}{dy}\right) - \frac{\sigma B_0^2 \left(w - mu + mU_0\right)}{\rho_f \left(1 + m^2\right)},$$
(3.2)

$$-V\frac{dT}{dy} = \alpha_f \frac{d^2T}{dy^2} + \frac{\mu_f}{(\rho c_p)_f} \left( \left( \frac{du}{dy} \right)^2 + \left( \frac{dw}{dy} \right)^2 \right) + \frac{\sigma B_0^2}{\left( \rho c_p \right)_f} \left( \frac{(u - U_0 + mu)^2 + (w - mu + mU_0)^2}{\left( 1 + m^2 \right)^2} \right)$$
$$-\tau \left( D_B \frac{dT}{dy} \frac{dC}{dy} + \frac{D_T}{T_f} \left( \frac{dT}{dy} \right)^2 \right),$$

(3.3)

$$-V\frac{dC}{dy} = D_B \frac{d^2C}{dy^2} + \left(\frac{D_T}{T_f}\right) \left(\frac{d^2T}{dy^2}\right).$$
(3.4)

The dynamical viscosity is the function of temperature which is

$$\mu(T) = e^{-\beta(-T_f + T)} \mu_0. \tag{3.5}$$

The BCs are as under

$$u = w = 0, C = C_0, -k \frac{dT}{dy} = h_f (T_f - T), at \ y = 0,$$
  
$$u = U_0 T = T_1, C = C_1, w = 0, \text{at } y = L.$$
  
(3.6)

The dimensionless variables are used to make equation dimesionless

$$\eta = \frac{y}{L}, X = \frac{x}{L}, \theta = \frac{-T_f + T}{-T_f + T_1}, \phi = \frac{-C_0 + C}{-C_0 + C_1}, \delta = \beta(-T_f + T_1), \upsilon = \frac{\mu_0}{\rho_f},$$

$$U = \frac{uL}{\upsilon}, W = \frac{wL}{\upsilon}, Bi = \frac{Lh_f}{k}, \Pr = \frac{\upsilon}{\alpha_f}, \alpha_f = \frac{k}{(\rho c_p)_f},$$

$$Ec = \frac{\upsilon}{C_{pf}(T_1 - T_f)L^2}, M = \frac{L^2 \sigma B_0^2}{\mu_0}, R_0 = \frac{\Omega L^2}{\upsilon}, Nb = \frac{\tau(C_1 - C_2)D_B}{\upsilon},$$

$$\overline{P} = \frac{PL^2}{\rho_f \upsilon^2}, Le = \frac{\alpha_f}{D_B}, Nt = \frac{\tau D_T (T_1 - T_f)}{T_f \upsilon}, \lambda = \frac{U_0 L}{\upsilon}, \operatorname{Re} = \frac{VL}{\upsilon}.$$
(3.7)

Now putting Eq. (3.7) into Eqs. (3.1) - (3.6), we get

$$-\operatorname{Re}\frac{dU}{d\eta} + 2RoW = e^{-\delta\theta}\frac{d^{2}U}{d\eta^{2}} - \delta e^{-\delta\theta}\frac{d\theta}{d\eta}\frac{dU}{d\eta} - \frac{M\left(U - \lambda + mW\right)}{\left(1 + m^{2}\right)},$$
(3.8)

$$-\operatorname{Re}\frac{dU}{d\eta} - 2Ro(U-\lambda) = e^{-\delta\theta}\frac{d^{2}W}{d\eta^{2}} - \delta e^{-\delta\theta}\frac{d\theta}{d\eta}\frac{dU}{d\eta} - \frac{M(W-mU+m\lambda)}{(1+m^{2})},$$
(3.9)

$$\frac{d^{2}\theta}{d\eta^{2}} + Re \operatorname{Pr} \frac{d\theta}{d\eta} + Nb \frac{d\varphi}{d\eta} \frac{d\theta}{d\eta} - \left(\frac{d\theta}{d\eta}\right)^{2} Nt + \operatorname{Pr} Ec \left(\left(\frac{dW}{d\eta}\right)^{2} + \left(\frac{dU}{d\eta}\right)^{2}\right) e^{-\delta\theta} + \operatorname{Pr} EcM \left(\frac{\left(U - mW + \lambda\right)^{2} + \left(W - m\lambda + mU\right)^{2}}{\left(1 + m^{2}\right)^{2}}\right) = 0,$$

$$\frac{d^{2}}{d\eta^{2}} (\phi) + \operatorname{Pr} Le \operatorname{Re} \frac{d}{d\eta} (\phi) + \frac{Nb}{Nt} \frac{d^{2}}{d\eta^{2}} (\theta) = 0,$$
(3.11)

with BCs

$$W(0) = U(0) = 0, \ \frac{d\theta}{d\eta}(0) = \theta(0)Bi, \ \phi(0) = 0,$$
  

$$W(1) = 0, \ U(1) = \lambda, \ \theta(1) = \phi(1) = 1.$$
(3.12)

The special cases for Eq. (3.8) are also studied and solution of these cases are presented. Case 1: Where  $\delta = \text{Re} = M = Ro = 0$ , Eq. (3.8) becomes

$$U''(\eta) = 0,$$
 (3.13)

with BCs

$$U(1) = U(0) = \lambda.$$
(3.14)

The exact solution of Eq. (3.13) from 3.14

$$U = \eta \lambda \,. \tag{3.15}$$

**Case 2**: When  $\delta = m = Ro = Re = 0$ , Eq. (3.8) becomes:

$$U''(\eta) - M(U - \lambda) = 0,$$
 (3.16)

with Eq. (3.14).

The solution of Eq. (3.16) is

$$U = \lambda \left( -\frac{e^{\sqrt{M}(1-\eta)}}{\left( -e^{-\sqrt{M}} + e^{\sqrt{M}} \right)} + \frac{e^{\sqrt{M}(\eta-1)}}{\left( -e^{-\sqrt{M}} + e^{\sqrt{M}} \right)} + 1 \right).$$
(3.17)

**Case 3.** When  $\delta = M = Ro = 0$ , Eq. (3.8) becomes:

$$U'(\eta) + ReU'(\eta) = 0,$$
  
(3.18)  
with Eq. (3.14).

Eq. (3.18) becomes:

$$U = \lambda \left(\frac{-1 + e^{-\eta \operatorname{Re}}}{e^{-\operatorname{Re}} - 1}\right).$$
(3.19)

Here we also used some important quantities of surface skin friction, Nusselt number and Sherwood number at both surface which are given as under:

$$Cf_{1} = \frac{L^{2}\tau_{1}}{\rho\upsilon^{2}} = e^{-\delta\theta} \frac{dU}{d\eta}\Big|_{\eta=0,1}, \quad Cf_{2} = \frac{L^{2}\tau_{2}}{\rho\upsilon^{2}} = e^{-\delta\theta} \frac{dW}{d\eta}\Big|_{\eta=0,1},$$

$$Nu = \frac{Lq_{m}}{k(T_{1} - T_{f})} = -\frac{d\theta}{d\eta}\Big|_{\eta=0,1}, \quad Sh = \frac{Lq_{w}}{D_{B}(CC_{1} - C_{0})} = -\frac{d\varphi}{d\eta}\Big|_{\eta=0,1}$$
(3.20)

where

$$\tau_1 = \mu \frac{du}{dy}, \ \tau_2 = \mu \frac{dw}{dy}, \ q_{_m} = -k \frac{dT}{dy}, \ q_{_w} = -D_B \frac{dC}{dy}.$$
(3.21)

#### **3.2 Results and Discussion**

By using RK-method, MHD Coutte-Poiseuille (CP) flow is numerically inspected with mass & heat transfer in a rotating channel. To check numerical results, we compared these results with exact solutions for some particular cases which are presented in Table 3.1. Hence the results conducted by comparison methods proved that numerical method is more efficient than exact solution.

Figure 3.2(a) and 3.2(b) clearly show the effect of M and viscosity on  $U(\eta)$  and  $W(\eta)$ .

 $U(\eta)$  increased by increasing the value of both parameters. For larger values of M with  $\delta$  as shown in Figure 3.2(a)  $U(\eta)$  converges very fast. Similarly the same result shows in Figure 3.2(b) for  $W(\eta)$ . The consequences of the reality, magnetic field is usually reduced the velocity gradient and  $W(\eta)$  is zero with the hydrodynamic BC for surface.

Figure 3.3(a) and 3.3(b) describe the influence of m and Re on  $U(\eta)$  and  $W(\eta)$ 

. In these Figures, due to the presence of m we note that the  $U(\eta)$  decreased uniformly and also for larger values of Re it converges rapidly.  $U(\eta)$  and  $W(\eta)$  decreased by increasing the values of m.

Figure 3.4(a) & 3.4 (b) depict the influence of  $\lambda$  and  $R_0$  on  $U(\eta)$  and  $W(\eta)$ .  $U(\eta)$ increased with  $\lambda$  and  $R_0$ , whereas its value zero at the bottom. Figure 3.5(a) and 3.5(b) show the effects of  $R_0$ , Re,  $\lambda$  & M on the  $\theta(\eta)$ . The  $\theta(\eta)$  increased with  $\lambda$  and  $R_0$ , as describes in Figure 3.5(a). Additionally,  $\theta(\eta)$  increased for larger values of Re.

In Figures 3.6(a) and 3.6(b) show the influence of Bi and Ec on  $\theta(\eta)$  in addition with mand  $\delta \cdot \theta(\eta)$  decreased for both parameters i.e m and  $\delta$ .

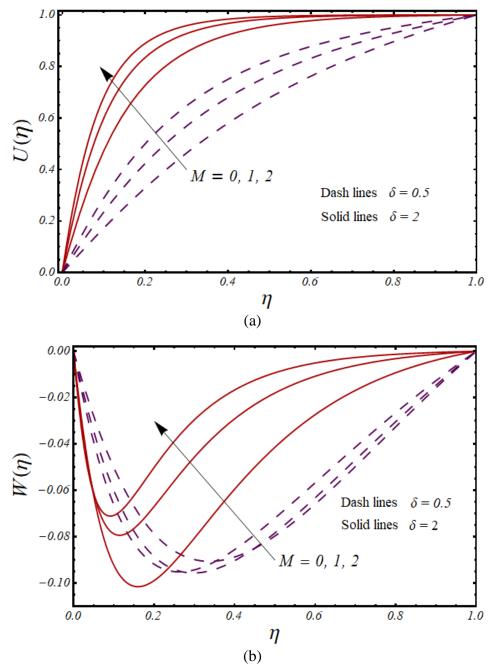
The impact of magnetic parameters for primary flow on  $Cf_1$  at top and bottom between parallel walls with  $\lambda$  and  $R_0$  are described in Figures 3.7(a) and 3.7(b). Skin friction is examined to be decreased and increased just because of magnetic field.  $Cf_1$  at top surface changes from bottom surface and with smaller values of  $R_0$ ,  $\lambda$  as presented in Figure 3.7(b).

The impact of secondary flow in two parallel walls on the bottom surface for  $Cf_2$  with  $\lambda$ ,  $R_0$ , Re and magnetic parameters are shown in Figure 3.8(a) and 3.8(b). Since in the secondary flow, due to magnetic field and  $R_0$ ,  $Cf_2$  at lower surface is decreased. Figures 3.9(a) and (b) elucidates the influence of dimensional number and appropriate NF main flow parameters at the top and bottom on Nu. It is also observed that Ec,  $R_0$  and Nu at lower surface decreased with M in Figure 3.9(a) and therefore the heat exchange rate is reduced. Figure 3.9(b) depicts that Nu decreases but for upper surface motion is increased with Ec.

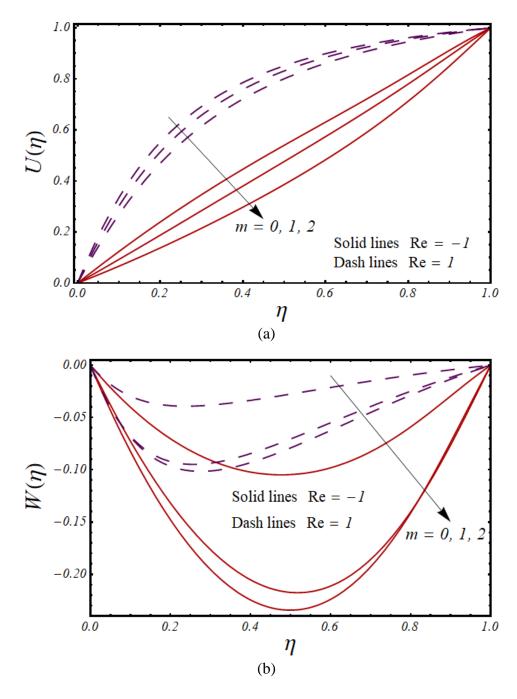
The effects of *Sh* for primary flow with *Le* is depicted in Figures 3.10(a) and 3.10(b) at bottom and top. *Sh* decreases with *Nb* and *Le* at both of bottom and top surfaces.

η	Case 1: $\delta = Re = M = Ro = 0$		Case 2: $\delta = Re = m = Ro = 0$		Case 3: $\delta = Ro = M = 0$	
	Numerical	Exact	Numerical	Exact	Numerical	Exact
0	0	0	0	0	0	0
0.1	0.05	0.05	0.0569	0.0570	0.0753	0.0753
0.2	0.10	0.10	0.1115	0.1116	0.1434	0.1433
0.3	0.15	0.15	0.1642	0.1642	0.2050	0.2050
0.4	0.20	0.20	0.2153	0.2153	0.2607	0.2607
0.5	0.25	0.25	0.2649	0.2649	0.3112	0.3113
0.6	0.30	0.30	0.3133	0.3134	0.3568	0.3569
0.7	0.35	0.35	0.3608	0.3606	0.3982	0.3982
0.8	0.40	0.40	0.4076	0.4076	0.4356	0.4357
0.9	0.45	0.45	0.4539	0.4539	0.4694	0.4694
1	0.50	0.50	0.5000	0.4999	0.5000	0.5000

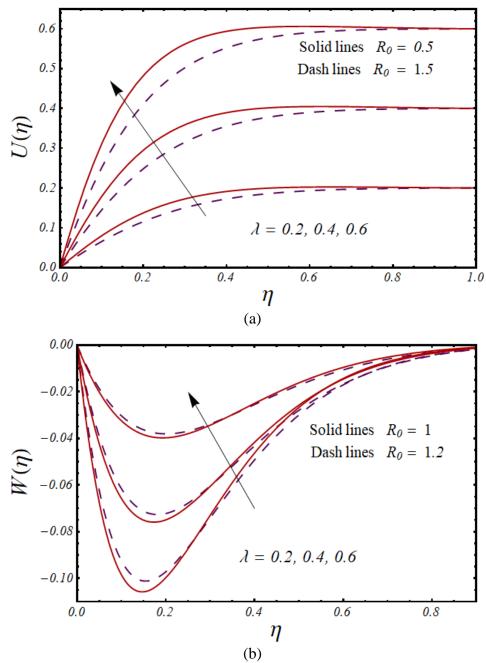
**Table 3.1:** Comparison of exact and numerical outcomes of  $U(\eta)$ .



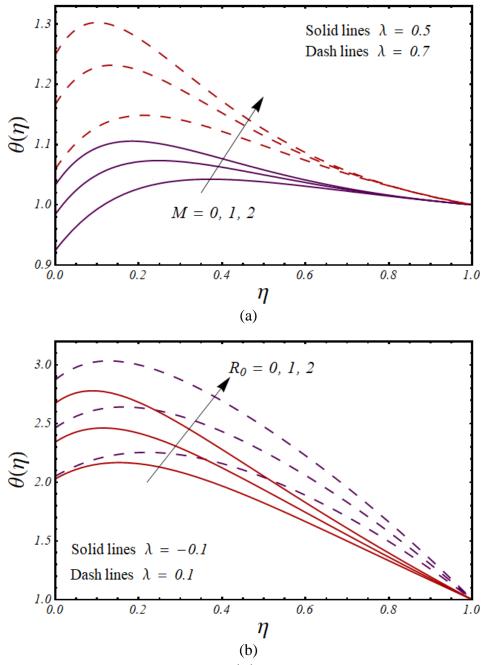
**Figure 3.2:**  $U(\eta)$  and  $W(\eta)$  with M.



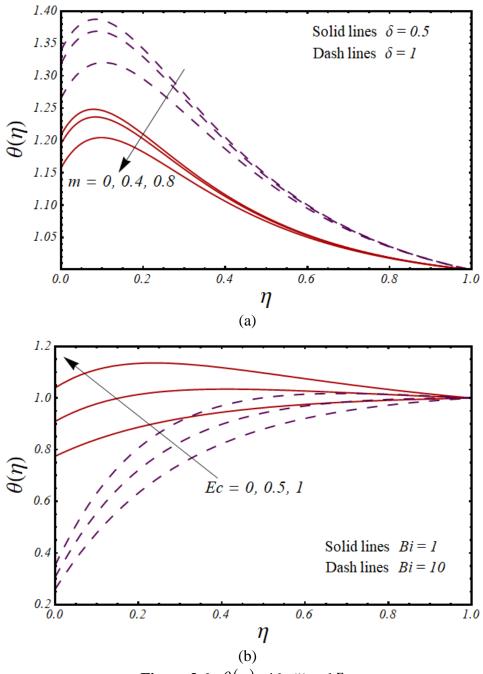
**Figure 3.3:**  $U(\eta)$  and  $W(\eta)$  with  $\mathcal{M}$ .



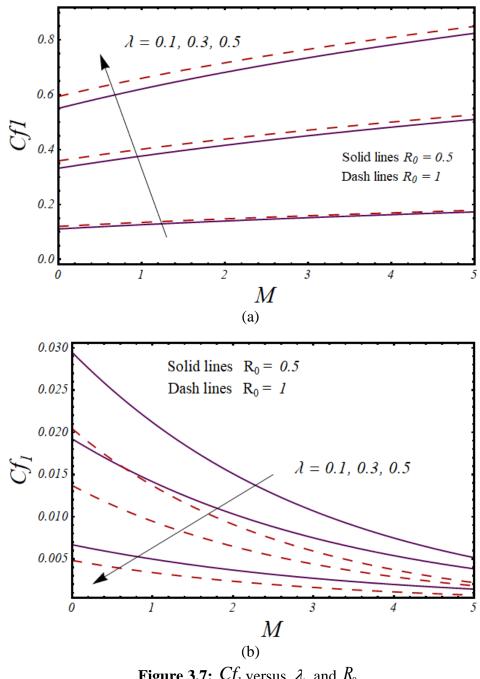
**Figure 3.4:**  $U(\eta)$  and  $W(\eta)$  with  $\lambda$ .



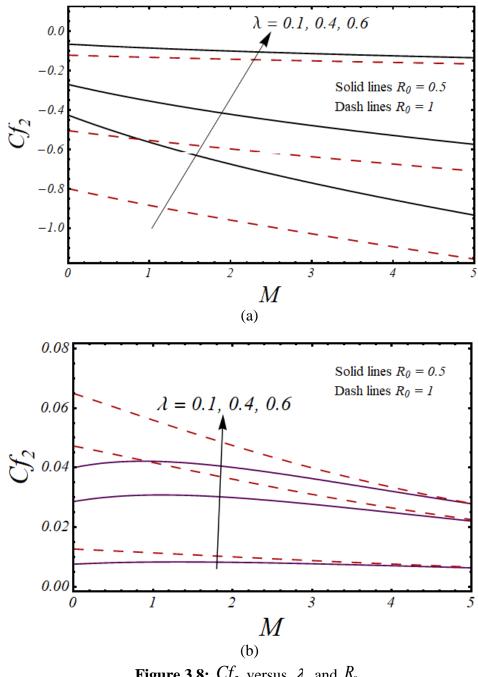
**Figure 3.5:**  $\theta(\eta)$  with *M* and  $R_0$ .



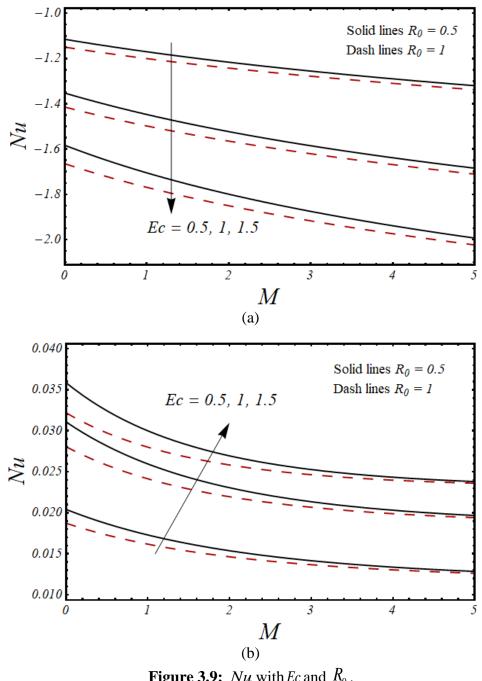
**Figure 3.6:**  $\theta(\eta)$  with *m* and *Ec*.



**Figure 3.7:**  $Cf_1$  versus  $\lambda$  and  $R_0$ .



**Figure 3.8:**  $Cf_2$  versus  $\lambda$  and  $R_0$ .



**Figure 3.9:** *Nu* with *Ec* and  $R_0$ .

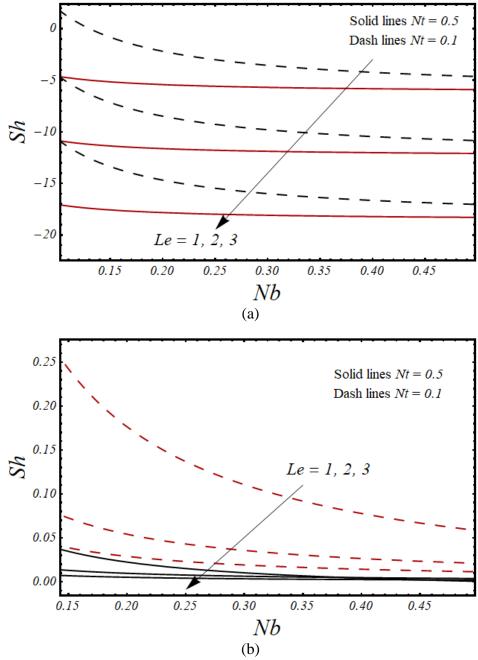


Figure 3.10: Sh with Le and Nt.

## **Chapter 4**

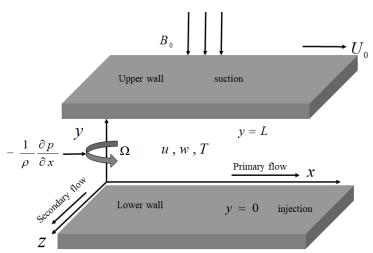
# Study of Couette-Poiseuille flow of kerosene based ferrofluid in a rotating channel with mass transfer and slip effect

### **4.1 Introduction**

This chapter presents an analysis on CP flow of kerosene based nanofluid in a rotating channel. The contribution of wall slip on the flow is examined with magnetic field. Mass transfer analysis is also carried out. In combination with non-linear ODEs, similarity transformation is used to transform the governing equations. For solution of these non-liner ODEs, the same procedure is adopted which applied in previous chapter. Finally, the results are shown via graphs.

#### **4.2 Problem Formulation**

Figure 4.1 reflects the geometry of the problem consisting of two infinite plates with temperatures  $T_1$  and  $T_f$  while  $h_f$  is the heat transfer coefficient. All physical parameters depend on y - axis expect pressure. The channel is filled with kerosene based FF and ferro particles (FP) (Ferrimagnetic cobalt ferrite ( $CoFe_2O_4$ )). Table 4.1 outlines the NF's thermo-physical characteristics.



**Figure 4.1:** Physical configuration of the problem The equations for flow fluid, under the above suppositions are as follows

$$-V\frac{du}{dy} + 2\Omega w = \frac{1}{\rho_{nf}}\frac{d}{dy}\left(\mu_{nf}\frac{du}{dy}\right) - \frac{\sigma_{nf}B_0^2\left(u - U_0 + mw\right)}{\rho_{nf}\left(1 + m^2\right)},\tag{4.1}$$

$$-V\frac{dw}{dy} - 2\Omega(u - U_0) = \frac{1}{\rho_{nf}} \frac{d}{dy} \left(\mu_{nf} \frac{dw}{dy}\right) - \frac{\sigma_{nf} B_0^2 \left(w - mu + mU_0\right)}{\rho_{nf} \left(1 + m^2\right)},\tag{4.2}$$

$$-V\frac{dT}{dy} = \alpha_{nf}\frac{d^{2}T}{dy^{2}} + \frac{\mu_{nf}}{(\rho c_{p})_{nf}} \left( \left(\frac{du}{dy}\right)^{2} + \left(\frac{dw}{dy}\right)^{2} \right) + \frac{\sigma_{nf}B_{0}^{2}}{(\rho c_{p})_{nf}} \left( \frac{(u - U_{0} + mu)^{2} + (w - mu + mU_{0})^{2}}{(1 + m^{2})^{2}} \right), \quad (4.3)$$

$$-V\frac{dC}{dy} = D\frac{d^2C}{dy^2} - k_n (C_1 - C_0)^n.$$
(4.4)

$$\mu_{nf} = \frac{\mu_f}{\left(1-\varphi\right)^{2.5}}, \alpha_{nf} = \frac{\kappa_{nf}}{\left(\rho C_p\right)_{nf}}, \quad \rho_{nf} = \varphi \rho_s + (1-\varphi)\rho_f,$$

$$\frac{\kappa_{nf}}{\kappa_f} = \frac{\kappa_s + (n_p - 1)\kappa_f - (n_p - 1)\varphi\left(\kappa_f - \kappa_s\right)}{\kappa_s + (n_p - 1)\kappa_f + \varphi\left(\kappa_f - \kappa_s\right)}, \left(\rho C_p\right)_{nf} = (1-\varphi)\left(\rho C_p\right)_f + \varphi\left(\rho C_p\right)_s.$$
(4.5)

Here  $n_p = 3$  for spherical shaped and  $n_p = 1.5$  for cylindrical shaped [42].

Table 4.1 Thermo pl	hysical q	uantities of f	ferroparticle and	kerosene oil [42].
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Liquid/ NPs	ho (kg/m <sup>3</sup> )	$C_p(J/\text{kg K})$	<i>к</i> (W/m K)
Kerosene oil	783	2090	0.15
$CoFe_2O_4$	4907	700	3.7

The appropriate BCs of the present problem are

$$u = b_1 \frac{du}{dy}, \quad w = b_1 \frac{dw}{dy}, \quad C = C_0, \quad -k \frac{dT}{dy} = h_f (T_f - T), \text{ at } y = 0,$$
  
$$u = U_0, \quad C = C_1, \quad T = T_1, \quad w = 0 \text{ at } y = L.$$
(4.6)

Here  $b_1$  is the velocity slip length.

By using equation (3.7) and the following dimensionless quantities

Sc = 
$$\frac{L\nu}{D}$$
,  $\gamma = k_n \frac{L}{\nu} (C_1 - C_0)^{n-1}$ ,  $\alpha = b_1 \frac{\nu_f}{L^2}$ , (4.7)

Eqs. (4.1)-(4.7) become

$$-Re\frac{dU}{d\eta} + 2RoW = \frac{1}{A_1A_2} \left( -\delta e^{-\delta\theta} \frac{d\theta}{d\eta} \frac{dU}{d\eta} + e^{-\delta\theta} \frac{d^2U}{d\eta^2} \right) - \frac{1}{A_1} \left( \frac{M\left(mW + U - \lambda\right)}{\left(m^2 + 1\right)} \right), \quad (4.8)$$

$$-Re\frac{dU}{d\eta} - 2Ro(U - \lambda) = \frac{1}{A_1 A_2} \left( e^{-\delta\theta} \frac{d^2 W}{d\eta^2} - \delta e^{-\delta\theta} \frac{d\theta}{d\eta} \frac{dU}{d\eta} \right) - \frac{1}{A_1} \left( \frac{M(W - mU + m\lambda)}{(1 + m^2)} \right),$$
(4.9)

$$A_{4}\frac{d^{2}\theta}{d\eta^{2}} + A_{3}\operatorname{Re}\operatorname{Pr}\frac{d\theta}{d\eta} + \frac{1}{A_{1}}\left(Ec\left(\left(\frac{dU}{d\eta}\right)^{2} + \left(\frac{dW}{d\eta}\right)^{2}\right)\operatorname{Pr}e^{-\delta\theta}\right) + Ec\operatorname{Pr}M\left(\frac{\left(mW + U - \lambda\right)^{2} + \left(-mU + m\lambda + W\right)^{2}}{\left(1 + m^{2}\right)^{2}}\right) = 0,$$
(4.10)

$$\frac{d^2}{d\eta^2}(\phi) + Sc\left(\frac{d}{d\eta}(\phi)\right) \operatorname{Re}-\gamma \left(\frac{d}{d\eta}(\phi)\right)^n Sc = 0, \tag{4.11}$$

where

$$A_{1} = \varphi \frac{\rho_{s}}{\rho_{f}} + (-\varphi + 1), A_{2} = (1 - \varphi)^{2.5}, A_{3} = \varphi (\rho C_{p})_{s} \left(\frac{1}{(\rho C_{p})_{f}}\right) + (1 - \varphi),$$
$$A_{4} = \kappa_{nf} \left(\frac{1}{\kappa_{f}}\right) = \frac{\kappa_{s} + (n_{p} - 1)\kappa_{f} - \varphi (\kappa_{f} - \kappa_{s})(n_{p} - 1)}{\kappa_{s} + (n_{p} - 1)\kappa_{f} + \varphi (\kappa_{f} - \kappa_{s})}.$$

The BCs in new variables become

$$U(0) = \alpha \frac{dU}{d\eta}(0), \quad W(0) = \alpha \frac{dW}{d\eta}(0), \quad \frac{d\theta}{d\eta}(0) = Bi\theta(0), \quad \phi(0) = 0,$$
  

$$U(1) = \lambda, \quad W(1) = 0, \quad \theta(1) = 1, \quad \phi(1) = 1.$$
(4.12)

#### 4.2 Results and Discussion

The above mentioned governing equations (4.8)-(4.11) are solved with BCs at equation (3.12). Figure 4.2 explaines the influence of Re and M on  $U(\eta)$  and  $W(\eta)$  of fluid in a channel with the slip condition. From Figures 4.2(a)-4.2(b) we conclude that velocity increased by rising the values of Re, M and  $\alpha$  on lower wall.

The variation of slip parameter on fluid velocities  $U(\eta)$  and  $W(\eta)$  in the whole channel for different values of  $m, \lambda, R_0$  and  $\delta$  are expressed in Figures 4.3 - 4.4. Figure. 4.3(a)-4.3(b) show the effect on  $W(\eta)$  and  $U(\eta)$  for various values of  $\delta$  and  $\lambda$  with  $\alpha$ . From these Figures, fluid velocity is increased by the increasing values of  $\alpha$ . However, an increment in velocity profile is found by increasing the values of  $\lambda$  and  $\delta$ . Figure. 4.4(a) and 4.4(b) elucidate the effect of Hall and rotation parameters on primary and secondary velocities for zero and non-zero values of slip parameter. We can be observed the varying behavior of  $\alpha$  from figures and examined a rapid growth in primary & secondary fluid velocities.

The variation of  $\theta(\eta)$  with  $\lambda$ ,  $\delta$ , Ec, Bi, Re and  $R_0$  is shown in Figures 4.5-4.7. It can be seen that in Figure 4.5,  $\theta(\eta)$  increased with greater values of  $\lambda$  and  $\delta$ . Furthermore, Figure 4.6 demonstrates that temperature is decreased by Bi, however it increased by Ec. Similarly,  $\theta(\eta)$  is increased with  $R_0$ , whereas it is increased more with Re which is depicted in Figure 4.7. The curves shown in Figures 4.8 to 4.10 illustrate the diversity in  $U(\eta), W(\eta) \& \theta(\eta)$  with the escalating values of  $\emptyset$ . From these figures it can be seen that values of  $U(\eta), W(\eta)$  and  $\theta(\eta)$  increased by increasing the values of  $\emptyset$  along with Re and its decreased for smaller values of  $\emptyset$  with Re.

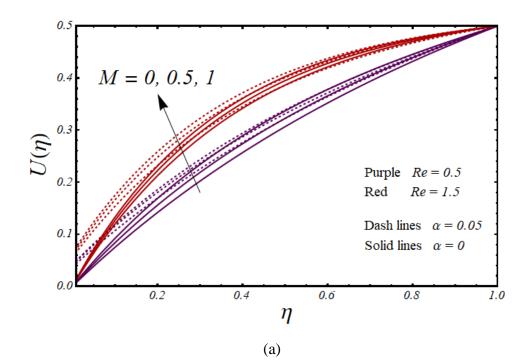
In order to examine that how *Sc* and *Re* effect  $\phi(\eta)$ , Figure 4.11 is presented. The value of  $\phi(\eta)$  increased gradually by increasing the values of *Sc* and *Re*. Since *Sc* relay inversely with the mass diffusion rate,  $\phi(\eta)$  decreased by increasing the *Sc*. Figure 4.12 depicts the alternation in  $\phi(\eta)$  with dissimilar number of *Sc* and  $\gamma$ . We may conclude from

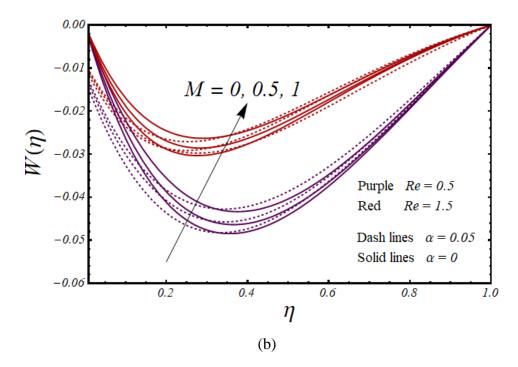
this figure that for greater values of  $\gamma$  and *Sc* there is an immense decrease in  $\phi(\eta)$  and increase in the concentration with a decrease of both parameters. An increment in  $\phi(\eta)$  can be clearly observed with rise in order shape factor *n* of the chemical reaction and *Sc* parameter which is presented in Figure 4.13.

Figure 4.14 is plotted to show the effects on skin friction with variation in  $\alpha$  and  $R_0$  for primary flow at lower & upper surfaces. This Figure shows that by the increasing the values of  $\alpha$ , skin friction is decreased at the lower wall. Figures 4.15(a) and 4.15(b) are presented to show the effects on skin friction with  $\lambda$  on primary velocity due to slip parameter of fluid at the bottom surface and top wall. With an increase  $\alpha$  and reduction in  $R_0$ , it is concluded that for primary flow the  $\lambda$  and  $\alpha$  decreased the  $Cf_1$  for both bottom and top surfaces.

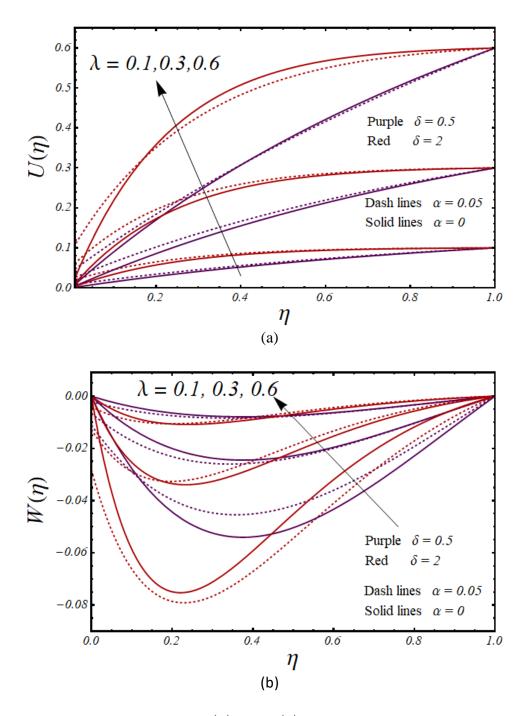
Figure 4.16 is presented to show the variation on  $Cf_2$  for primary flow with  $R_0$  and  $\alpha$  at lower & upper surfaces respectively through rotating channel. The  $Cf_2$  is increased by increasing the values of  $R_0$  while an escalation is found averse to  $\alpha$ . The variation of  $Cf_2$  with  $\lambda$  and  $\alpha$  for secondary flow at both surface is presented in Figure 4.17, in this regard, the secondary flow is noted,  $\lambda$  and M reduced the skin friction for top and bottom surfaces respectively.

The influence of M,  $R_0$  and  $\delta$  on Nu for primary flow of FF for surfaces is shown in Figure 4.18. It can be found that by increasing the valued of  $\delta$ , it decreases Nu. Figure 4.19 exhibits the effects on Sh with Sc and  $\gamma$  for primary flow at both surfaces respectively. The Figure show that an increment in Sc will increase Sh, however rise in  $\gamma$ implies the minor decrease in Sh for both surfaces. Figure 4.20(a) and 4.20(b) depict the influence on Sh with various values of Sc and Re. These Figure shows that for primary flow, for the greater values of Re, Sh increased at both lower and upper surfaces.

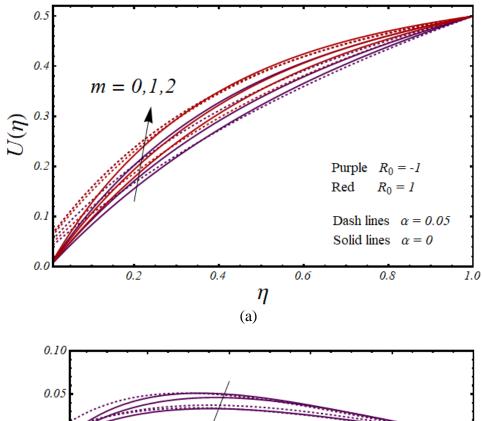


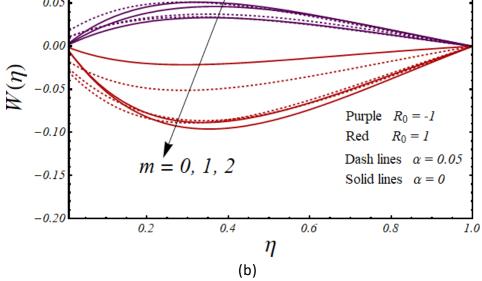


**Figure 4.2**:  $U(\eta)$  and  $W(\eta)$  with Re and  $\alpha$ .

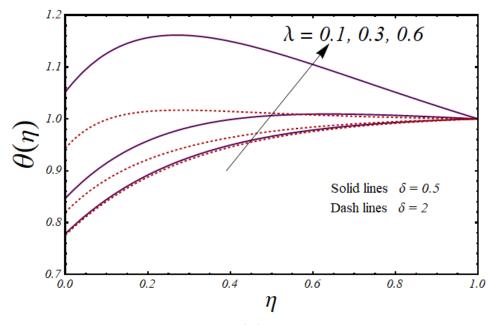


**Figure 4.3**:  $U(\eta)$  and  $W(\eta)$  with  $\lambda$  and  $\alpha$ .

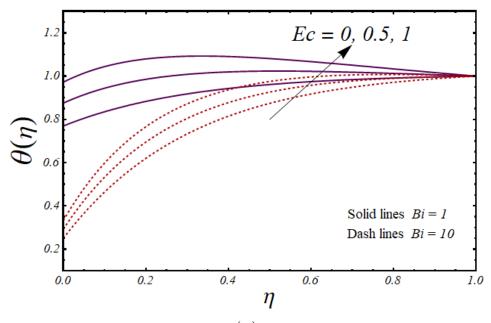




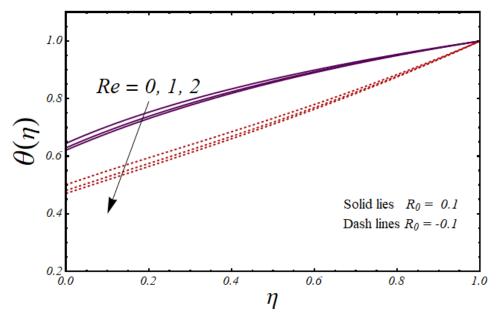
**Figure 4.4:**  $U(\eta)$  and  $W(\eta)$  with m and  $\alpha$ .



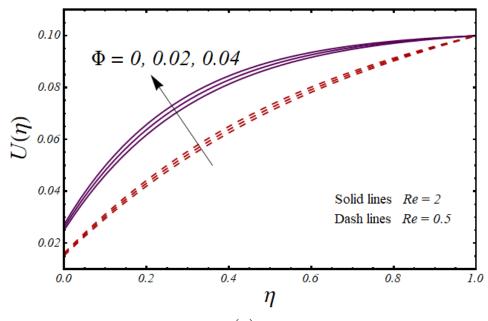
**Figure 4.5:**  $\theta(\eta)$  with  $\lambda$  and  $\delta$ .



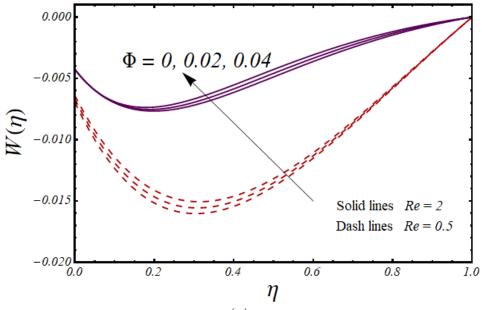
**Figure 4.6:**  $\theta(\eta)$  with *Ec* and *Bi*.



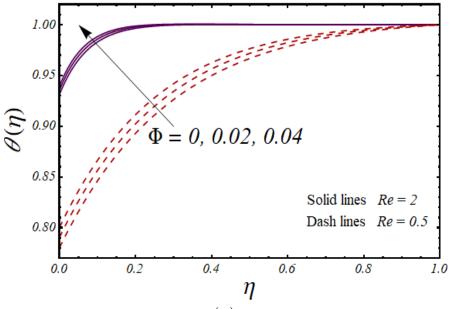
**Figure 4.7:**  $\theta(\eta)$  with Re and  $R_0$ .



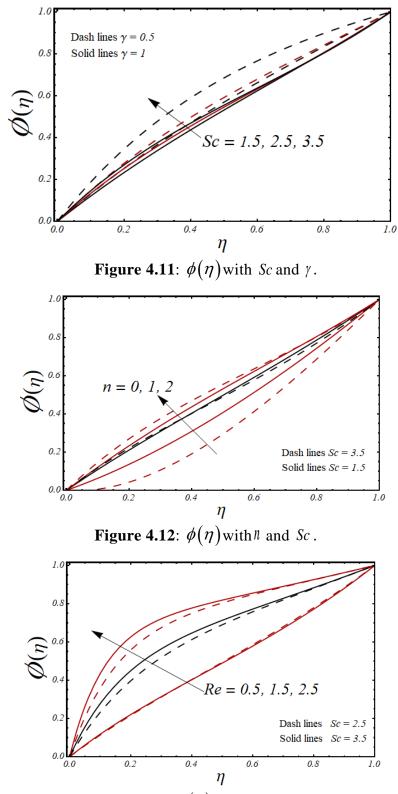
**Figure 4.8:**  $U(\eta)$  with  $\varphi$  and Re.



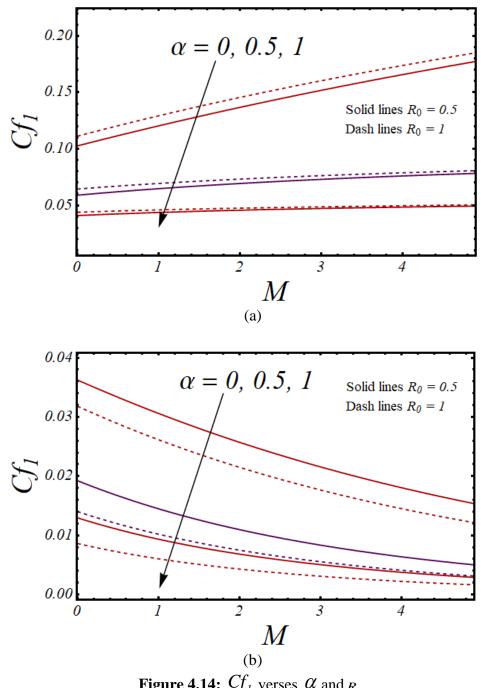
**Figure 4.9:**  $W(\eta)$  with  $\varphi$  and Re.



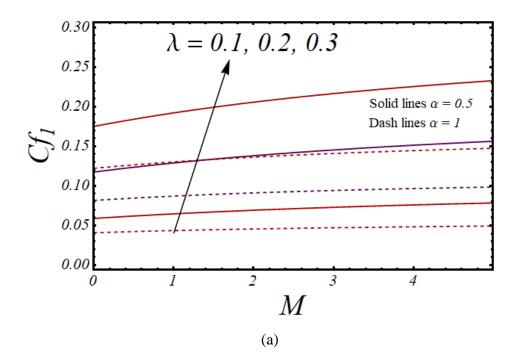
**Figure 4.10**:  $\theta(\eta)$  with  $\varphi$  and Re .

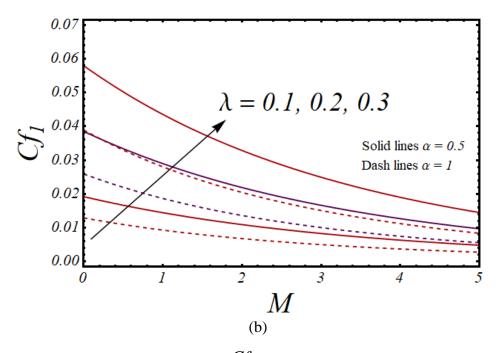


**Figure 4.13:**  $\phi(\eta)$  with Re and Sc.

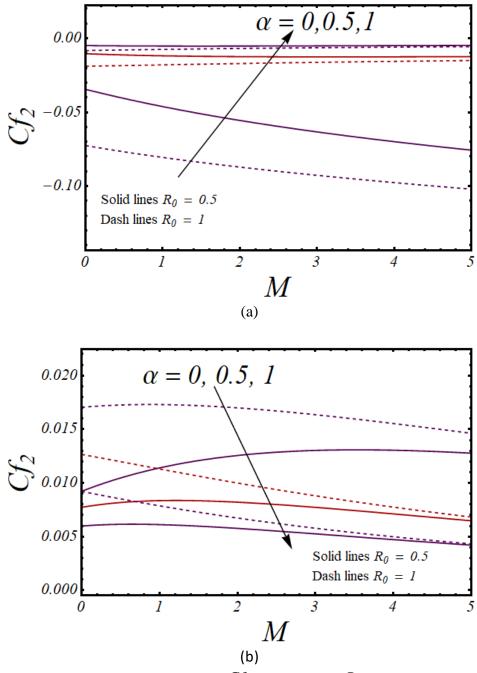


**Figure 4.14:**  $Cf_1$  verses  $\alpha$  and  $R_0$ .





**Figure 4.15:**  $Cf_1$  verses  $\lambda$  and  $\alpha$ .



**Figure 4.16:**  $Cf_2$  verses  $\alpha$  and  $R_0$ .

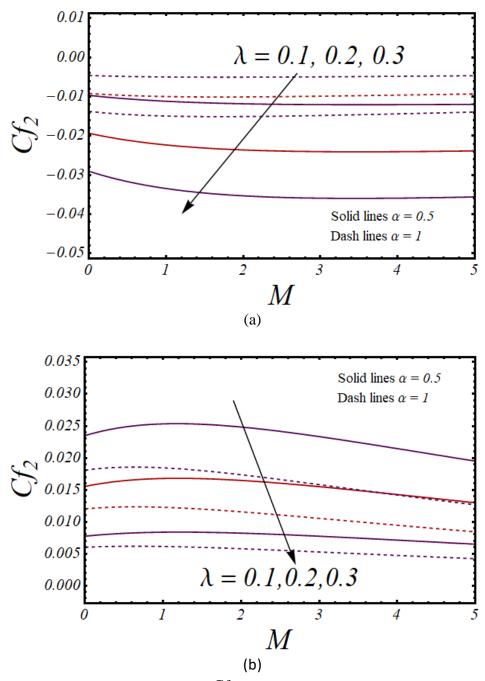
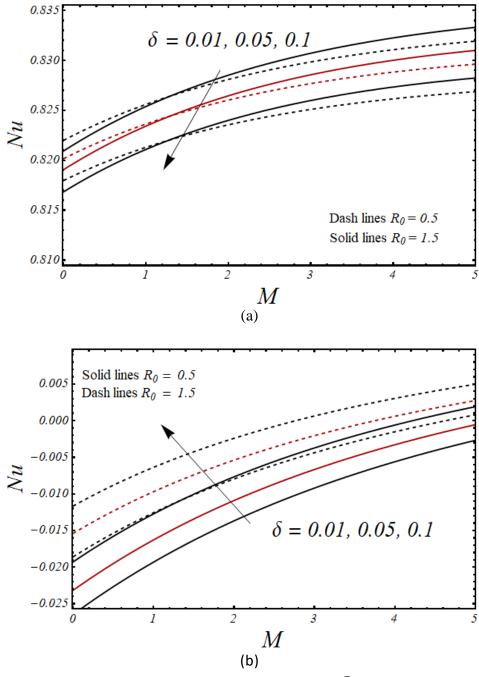
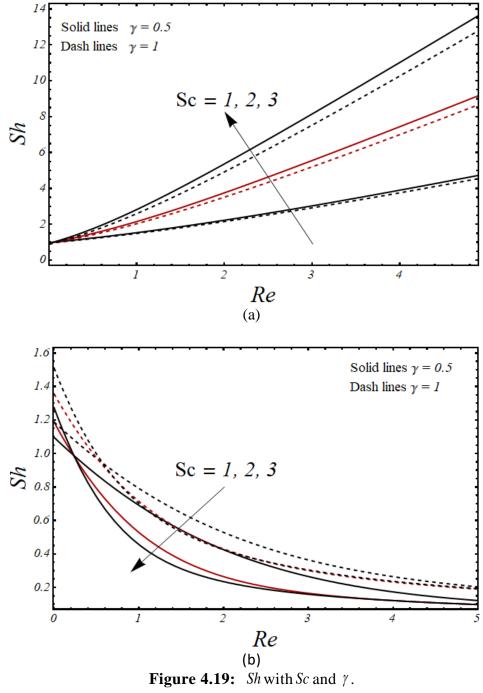
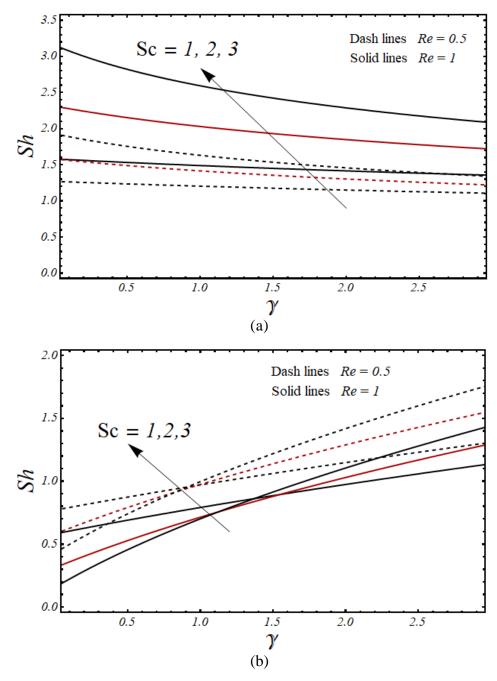


Figure 4.17:  $Cf_2$  verses with  $\lambda$  and  $\alpha$ .



**Figure 4.18:** Nu with  $\delta$  with  $R_0$ .





**Figure 4.20:** Sh with Sc and Re.

## **Chapter 5**

# **Conclusion**.

We extended our problem by considering CP flow of kerosene based FF in a rotating channel. By considering Tiwari & Das model in which the contribution of wall slip on the flow is also used in the presence of magnetic field whereas mass transfer analysis is carried out. The ferroparticles ( $_{COFe_2O_4}$ ) are added to the based fluid (Kerosene). We examined the behavior of velocity, temperature and skin friction with help of different parameters i.e  $M, \lambda, Re, R_0, \delta, Sc, \gamma$  and  $\alpha$ . For solution of the equations we used some numerical methods i.e R-K and shooting. All the governing parameters on different fields are presented via graphs. Some momentous observations of this chapter 4 can be summarized as follows:

- $U(\eta)$  increased with  $\lambda$ ,  $\delta$ , M, Re, m and  $R_0$  along with zero and non-zero slip parameter at the lower wall.
- $W(\eta)$  dncreased with  $\lambda$ ,  $\delta$ , M, Re, m and  $R_0$  along with zero and non-zero slip parameter at the lower wall.
- Values of U(η),W(η)&θ(η) are increased for greater values of φ and reduced for smaller values of φ with *Re*.
- The  $Cf_1$  and  $Cf_2$  increased with an increment of  $\alpha$  and  $R_0$  at lower surface whereas it reduced with the reduction of both parameter at upper surface for both primary and secondary flow.
- $\phi(\eta)$  enhanced by the greater value of *Sc* along with of  $\gamma$ .
- $\phi(\eta)$  is also increased by the increasing value of n and Re with the presence of Sc.

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